## **Tampere University of Technology** DEE-34106 Converter Dynamics and EMC 31.10. 2017 Electrical Energy Engineering

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Programmable calculator allowed

5 questions/ á 6 pts

Question 1. Fig. 1 shows an electrical equivalent circuit representing the dynamics of DDR-controlled second-order switched-mode converters operating in CCM. Define symbolically based on Fig. 1 a)  $Z_{\text{o-o}}$  (i.e.,  $\hat{v_{\text{o}}}/\hat{t_{\text{o}}}$ ), b)  $Z_{\text{in-o}}$  (i.e.,  $\hat{v_{\text{in}}}/\hat{t_{\text{in}}}$ ), and c)  $G_{\text{io-o}}$  (i.e.,  $\hat{v_{\text{o}}}/\hat{v_{\text{in}}}$ ). Each correct answer gives 2 pts.

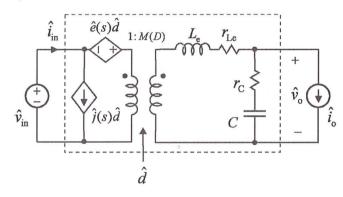


Fig. 1

Question 2. Fig. 2 shows the measured input impedances of a DDR-controlled buck converter equipped with an LC input filter  $(Z_s)$ .

- a) Is the converter stable? (Justify your answer)
- b) What is the approximate crossover frequency of the output-voltage feedback loop?
- c) The open-loop input impedance  $(Z_{\text{in-o}})$ , and the LC-filter output impedance  $(Z_{\text{s}})$  overlaps as visible in the figure. What effect this overlap has in the converter?

Each correct answer gives 2 pts.

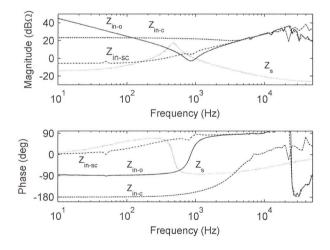


Fig. 2

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**Question 3.** A typical complementary sensitive function (T(s)) of a closed-loop system can be given by according to Eq. (1).

$$T(s) = \frac{\omega_n^2}{s^2 + s2\zeta\omega_n + \omega_n^2}$$
 (1)

- a) Explain the meaning of  $\zeta$  and  $\omega_n$ .
- b) Derive the expression for the loop gain L(s) based on Eq. (1).
- c) If  $2\zeta\omega_n < 0$  then how many RHP poles will exist in the system?

Each correct answer will give 2 pts.

Question 4. If we know that the set of transfer functions (i.e., G parameters) of the converter in Fig. 3a can be given by

$$\begin{bmatrix} \hat{i}_{\text{in}} \\ \hat{v}_{\text{o}} \end{bmatrix} = \begin{bmatrix} Y_{\text{in}}^{\text{G}} & T_{\text{oi}}^{\text{G}} & G_{\text{ci}}^{\text{G}} \\ G_{\text{io}}^{\text{G}} & -Z_{\text{o}}^{\text{G}} & G_{\text{co}}^{\text{G}} \end{bmatrix} \begin{bmatrix} \hat{v}_{\text{in}} \\ \hat{i}_{\text{o}} \\ \hat{d} \end{bmatrix}$$
 (2)

then compute the corresponding set of transfer functions (i.e., Y parameters) representing the dynamics of the converter in Fig. 3b according to

$$\begin{bmatrix} \hat{i}_{\text{in}} \\ \hat{i}_{\text{o}} \end{bmatrix} = \begin{bmatrix} Y_{\text{in}}^{\text{Y}} & T_{\text{oi}}^{\text{Y}} & G_{\text{ci}}^{\text{Y}} \\ G_{\text{io}}^{\text{Y}} & -Y_{\text{o}}^{\text{Y}} & G_{\text{co}}^{\text{Y}} \end{bmatrix} \begin{bmatrix} \hat{v}_{\text{in}} \\ \hat{v}_{\text{o}} \\ \hat{d} \end{bmatrix}$$
(3)

The power stage of the converter is the same all the time.

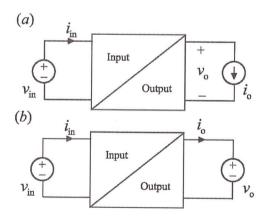


Fig. 3 VF-converter (a) voltage-output mode, and (b) current-output mode.

Each correct transfer function will give 1 pt.

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- Question 5. Fig. 4 shows the Bode plot of the open-loop output impedance of a buck converter. Its analytic form is given in Eq. (4).
  - a) Estimate the values of L, C,  $r_L$ , and  $r_C$  based on Fig. 4 (Each correct value gives 1 pt)
  - b) What is the characteristic impedance of this circuit and what is its value? (2 pts)

$$Z_{\text{o-o}} = \frac{1}{LC} \cdot \frac{(r_{\text{L}} + sL)(1 + sr_{\text{C}}C)}{s^2 + s\frac{r_{\text{L}} + r_{\text{C}}}{L} + \frac{1}{LC}}$$
(4)

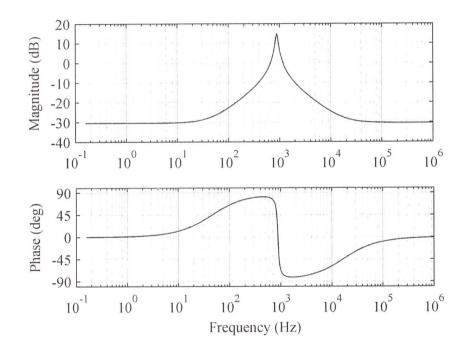


Fig. 4