

Exam of the course DEE-33106 Switched-mode converters, 5 cr.

Please answer all of the **five (5)** questions. The use of calculator is allowed. Please answer in Finnish or English.

Question 1: Answer TRUE or FALSE (+0.5 for correct, -0.5 for incorrect, 0 for empty, total max 8 p.)

- In steady state sum of ampere-seconds in capacitor is zero during one switching period
- In a given circuit increasing the inductor value decreases current ripple
- Unit of inductance (H) can also be presented in SI units as Vs/A
- Ideal capacitor would create an ideal current source
- Converter goes from CCM to DCM when load resistance increases significantly
- Capacitor parasitic inductance starts to dominate the impedance value on very high frequencies
- Mosfet is controlled by voltage signal to transistor gate
- Ceramic capacitors have higher ESR than electrolyte capacitors
- Inductor AC losses can be calculated if numbers of turns and switching frequency are known
- Doubling switching frequency doubles the switching losses in transistor
- Faster transistor rise time causes less current harmonics
- Capacitor has both AC and DC losses
- When inductor is saturated, inductance value decreases with increasing current
- Power factor correction means having more accurate square waves
- Normally it is best to build tailored control mechanism instead of using existing ICs
- EMC immunity means that device is not emitting electromagnetic waves

Question 2 (6 p.)

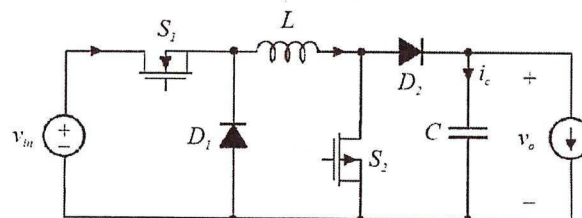


Figure 1: A non-inverting buck-boost converter

Fig. 1 shows a non-inverting buck-boost converter, which can be operated at three different modes: boost, buck-boost, and buck.

Mode 1: The switch S_2 is constantly OFF and switch S_1 is operated normally with duty ratio D .

Mode 2: The switch S_1 is constantly ON and switch S_2 is operated normally with duty ratio D .

Mode 3: The switches are operated together with duty ratio D (that is, both switches either conduct or not conduct in unison)

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Draw on-time and off-time circuits for each operation mode (2 pts)

- Define symbolically the conversion ratio $M(D)$ from input to output voltage for each operation mode (2 pts)
- Identify the operation modes (1 pts)
- Briefly discuss the downsides of using this converter topology (1 pts)

Question 3 (6 p.)

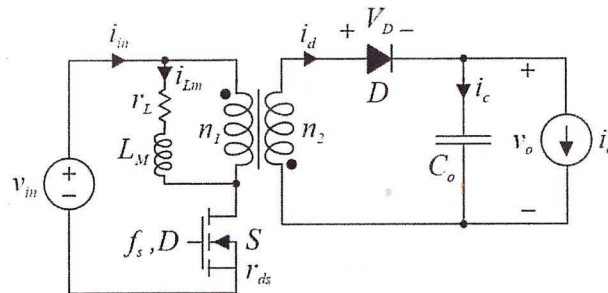


Figure 2: A non-ideal flyback converter

$$\begin{array}{llll}
 V_{in} = 340 \text{ V} & V_o = 60 \text{ V} & f_s = 10 \text{ kHz} & I_o = 2.5 \text{ A} \\
 V_D = 0.7 \text{ V} & r_{ds} = 100 \text{ m}\Omega & r_L = 100 \text{ m}\Omega & n = \frac{n_2}{n_1} = 0.26
 \end{array}$$

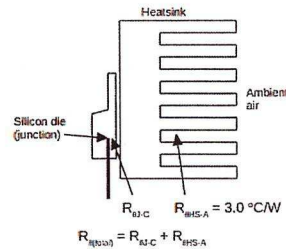
Fig. 2 shows a flyback converter with non-ideal magnetizing inductor, switch, and diode. The transformer and capacitor can be assumed ideal. Take the diode voltage drop, switch resistance and inductor resistance into account in calculations.

- Calculate the voltage over the transistor during off-time (1 pts)
- Solve the duty ratio and average inductor current (3 pts)
- Design output capacitor so that the output voltage peak-to-peak ripple is 5 V (2 pts)

Question 4 (6 p.)

A boost converter (such as one used in a PFC stage) is designed with the following parameters:

Input voltage	325 V DC
Input current	10.0 A DC
Output voltage	420 V DC
f_{sw}	100 kHz
V_{gs}	10V
$t_{ambient}$	50 °C
Diode heatsink R_{th}	3.0 °C/W



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Following components are used (datasheets included, please check carefully per component!):

MOSFET	IPW65R045C7
Diode	IDH16G65C5
Inductor	500 uH
Output capacitor	1500uF, 450V electrolytic

- Calculate MOSFET and diode conduction losses in worst case
- Calculate other types of diode losses, and diode die temperature, worst case
- After a failed EMC test, you have to add gate resistance $R_g=10\Omega$. Calculate MOSFET switching loss.

Question 5 (6 p.)

- Explain in sufficient detail how inductor works in switched mode converters. Include picture(s) and equations of basic principles and describe also coupled inductor.
- You have been asked to design a dc-dc converter for a small solar installation where a battery system would be charged. Describe the strategy on how to make a usable switch mode converter. What needs to be taken into account?

HELP for the exam

Second order equation solution: $ax^2 + bx + c = 0 \rightarrow x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$

Appendix A - Waveform Formulas

Waveform	I_{rms}	I_{dc}	$I_{ac(rms)}$
	I_{dc}	I_{dc}	0
	I_p	0	I_p
	$I_p \sqrt{D}$	$D I_p$	$I_p \sqrt{D(1-D)}$
	$I_p \sqrt{D}$	0	$I_p \sqrt{D}$
	$I_p \sqrt{\frac{1}{3}}$	0	$I_p \sqrt{\frac{1}{3}}$
	$I_p \sqrt{\frac{1}{3}}$	0	$I_p \sqrt{\frac{1}{3}}$
	$I_p \sqrt{\frac{D}{3}}$	$\frac{D}{2} I_p$	$I_p \sqrt{\frac{D}{3} (1 - \frac{3}{4} D)}$

$$I_{dc}^2 + I_{ac(rms)}^2 = I_{rms}^2$$

APPENDICES

Appendix A - Waveform Formulas

Waveform	I_{rms}	I_{dc}	$I_{ac(rms)}$
	$\frac{I_p}{\sqrt{2}}$	0	$\frac{I_p}{\sqrt{2}}$
	$I_p \sqrt{\frac{1}{3}}$	0	$I_p \sqrt{\frac{1}{3}}$
	$I_p \sqrt{\frac{D}{3}}$	$\frac{2D}{\pi} I_p$	$I_p \sqrt{\frac{D}{3} - \frac{4D^2}{\pi^2}}$
	$\frac{I_p}{\sqrt{2}}$	$\frac{2D}{\pi} I_p$	$I_p \sqrt{\frac{1}{2} - \frac{4D^2}{\pi^2}}$
	$\frac{I_p}{\sqrt{2}}$	0	$\frac{I_p}{\sqrt{2}}$
	$I_p \sqrt{\frac{1}{3}}$	0	$I_p \sqrt{\frac{1}{3}}$
	$I_p \sqrt{\frac{D}{3}}$	$\frac{D}{2} I_p$	$I_p \sqrt{\frac{D}{3} (1 - \frac{3}{4} D)}$